

Lectur 07: MAB Lower Bounds

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1 Sample complexity lower bound for (ϵ, δ) -PAC learning algorithms for best-arm identification

In this lecture we consider a warm-up case for MAB lower bound. In particular, we consider a MAB with 2 arms, and the goal is to identify the best arm. The final goal is to prove the following lower bound theorem, which matches the current algorithmic upper bound,

Theorem 1. *Suppose algorithm \mathcal{A} is (ϵ, δ) -PAC and uses less than T samples, then $T \gtrsim \frac{\ln(\delta^{-1})}{\epsilon^2}$.*

Recall that the definition of a (ϵ, δ) -PAC algorithm is such that

$$\Pr[\mathcal{A} \text{ outputs an arm within } \epsilon \text{ of the best arm}] \geq 1 - \delta$$

To further simplify the analysis, we also assume \mathcal{A} is a deterministic algorithm.

Proposition 2. *Suppose a (ϵ, δ) -PAC algorithm \mathcal{A} exists, then $\exists \mathcal{A}'$ which is also (ϵ, δ) -PAC, and plays arm1 T times, arm2 T times, and outputs via a function $f : [0, 1]^T \times [0, 1]^T \rightarrow \{1, 2\}$.*

Thus we can further assume that the algorithm pulls arm1 and arm2 for T times each. Finally, we only consider Bernoulli reward case, i.e. $f : \{0, 1\}^T \times \{0, 1\}^T \rightarrow \{1, 2\}$.

To begin our analysis, we consider 2 cases

- Instance 1: $\mu_1 = p, \mu_2 = p + \epsilon$
- Instance 2: $\mu_1 = p + \epsilon, \mu_2 = p$

Then by the definition of (ϵ, δ) -PAC,

$$(1) \text{ Instance 1} \implies \Pr_{r \sim \mathcal{B}_p^{\otimes T} \otimes \mathcal{B}_{p+\epsilon}^{\otimes T}}[f(r) = 1] \leq \delta$$

$$(2) \text{ Instance 2} \implies \Pr_{r \sim \mathcal{B}_{p+\epsilon}^{\otimes T} \otimes \mathcal{B}_p^{\otimes T}}[f(r) = 2] \leq \delta$$

where \mathcal{B}_p represents Bernoulli distribution with mean p , and we let $\mathcal{B}_p^{\otimes T} \otimes \mathcal{B}_{p+\epsilon}^{\otimes T}$ be \mathcal{D}_1 , $\mathcal{B}_{p+\epsilon}^{\otimes T} \otimes \mathcal{B}_p^{\otimes T}$ be \mathcal{D}_2 . The intuition for the rest of the proof is that if T is small, then \mathcal{D}_1 is “close” to \mathcal{D}_2 , which would imply that $\Pr_{\mathcal{D}_1}[f(r) = 1] \approx \Pr_{\mathcal{D}_2}[f(r) = 1]$, but this would be a contradiction.

1.1 Aside: some results on information theory

In order to measure the "closeness" of \mathcal{D}_1 and \mathcal{D}_2 , we need to introduce some useful inequalities from information theory. For simplicity let's assume here all considered distributions are discrete distribution.

Definition 3. *The total variation distance between measure P, Q is*

$$\Delta(P, Q) = \frac{1}{2} \|P - Q\|_1 = \frac{1}{2} \sum_{a \in \Omega} |P(a) - Q(a)|$$

Remark 1. *The equivalent definition of total variation distance is*

$$\Delta(P, Q) = \max_{A \in \Omega} |P(A) - Q(A)|$$

Proof. Let $B = \{a \in \Omega : P(a) \geq Q(a)\}$, then for any A

$$\begin{aligned} |P(A) - Q(A)| &= |P(A \cap B) - Q(A \cap B) + P(A \cap \bar{B}) - Q(A \cap \bar{B})| \\ &\leq \max\{P(A \cap B) - Q(A \cap B), Q(A \cap \bar{B}) - P(A \cap \bar{B})\} \\ &\leq \max\{P(B) - Q(B), Q(\bar{B}) - P(\bar{B})\} \\ &= \frac{1}{2} [P(B) - Q(B) + Q(\bar{B}) - P(\bar{B})] \\ &= \frac{1}{2} \sum_{a \in \Omega} |P(a) - Q(a)| \end{aligned}$$

Also, if we choose $A = B$, the all the inequalities hold as equalities. □

For our current problem, we can let $A = \{f(r) = 1\}$, then by the definition of total variation, $|\mathcal{D}_1(A) - \mathcal{D}_2(A)| \leq \Delta(\mathcal{D}_1, \mathcal{D}_2)$. Also by (ϵ, δ) -PAC, $|\mathcal{D}_1(A) - \mathcal{D}_2(A)| \geq 1 - 2\delta$, thus our goal is to prove that if T is too small, $\Delta(\mathcal{D}_1, \mathcal{D}_2) \leq 1 - 2\delta$, which would give the contradiction.

1.2 Towards bounding $\Delta(\mathcal{D}_1, \mathcal{D}_2)$ with T samples

1.2.1 Approach 1: brute-force calculation

Since given T , both distributions are explicitly defined, we can calculate the total variation directly:

$$\begin{aligned} \mathcal{D}_1(r_1, r_2, \dots, r_T, r'_1, r'_2, \dots, r'_T) &= p^a (1-p)^{T-a} (p+\epsilon)^b (1-p-\epsilon)^{T-b} := \mathcal{D}_1(a, b) \\ \mathcal{D}_2(r_1, r_2, \dots, r_T, r'_1, r'_2, \dots, r'_T) &= (p+\epsilon)^a (1-p-\epsilon)^{T-a} p^b (1-p)^{T-b} := \mathcal{D}_2(a, b) \end{aligned}$$

where a is the number of times that 1 appears in r_1, r_2, \dots, r_T , b is the number of times that 1 appears in r'_1, r'_2, \dots, r'_T . Thus

$$\|\mathcal{D}_1 - \mathcal{D}_2\|_1 = \sum_{a,b} \binom{T}{a} \binom{T}{b} |\mathcal{D}_1(a, b) - \mathcal{D}_2(a, b)|$$

This could potentially produce the desired bound, but this method is problem-specific and not applicable to other problems.

1.2.2 Approach 2: leveraging the relation between KL-divergence and total variation

Definition 4. The Hellinger distance between P and Q is:

$$H(P, Q) := \left[\frac{1}{2} \sum_{a \in \Omega} \left(\sqrt{P(a)} - \sqrt{Q(a)} \right)^2 \right]^{\frac{1}{2}} = \frac{1}{\sqrt{2}} \left\| \sqrt{P} - \sqrt{Q} \right\|_2$$

where \sqrt{P} is the vector of $\left[\sqrt{P(a)}, \forall a \in \Omega \text{ in a fixed order} \right]$

Obviously we have $0 \leq H(P, Q)$, and the following fact:

Remark 2.

$$H^2(P, Q) = \frac{1}{2} \sum_{a \in \Omega} \left(P(a) + Q(a) - 2\sqrt{P(a)Q(a)} \right) = 1 - \sum_{a \in \Omega} \sqrt{P(a)Q(a)}$$

With the previous definitions and remarks we have the following lemma to sandwich $\Delta(P, Q)$:

Lemma 5.

$$H^2(P, Q) \leq \Delta(P, Q) \tag{3}$$

$$\leq \sqrt{H^2(P, Q)(2 - H^2(P, Q))} \tag{4}$$

$$\leq \sqrt{2}H(P, Q)$$

Proof. The last line of inequalities is trivial since $2 - H^2(P, Q) \leq 2$. To prove (3), we need to show:

$$\sum_{a \in \Omega} \left(\sqrt{P(a)} - \sqrt{Q(a)} \right)^2 \leq \sum_{a \in \Omega} |P(a) - Q(a)|$$

which can be implied from:

$$\begin{aligned} \forall a \in \Omega, \quad P(a) + Q(a) - 2\sqrt{P(a)Q(a)} &\leq |P(a) - Q(a)| \\ \Leftrightarrow \frac{P(a) + Q(a) - |P(a) - Q(a)|}{2} &\leq \sqrt{P(a)Q(a)} \\ \Leftrightarrow \min\{P(a), Q(a)\} &\leq \sqrt{P(a)Q(a)} \end{aligned}$$

where the last inequality is because of: $\min\{P(a), Q(a)\} \equiv \frac{P(a)+Q(a)-|P(a)-Q(a)|}{2}$

The proof of (4) is as following:

$$\begin{aligned} \Delta^2(P, Q) &= \frac{1}{4} \left(\sum_{a \in \Omega} |P(a) - Q(a)| \right)^2 = \frac{1}{4} \left(\sum_{a \in \Omega} \left| \sqrt{P(a)} - \sqrt{Q(a)} \right| \left(\sqrt{P(a)} + \sqrt{Q(a)} \right) \right)^2 \\ \text{(C-S inequality)} &\leq \frac{1}{4} \left(\sum_{a \in \Omega} \left(\sqrt{P(a)} - \sqrt{Q(a)} \right)^2 \right) \left(\sum_{a \in \Omega} \left(\sqrt{P(a)} + \sqrt{Q(a)} \right)^2 \right) \\ &= \frac{1}{2} H^2(P, Q) \left(\sum_{a \in \Omega} \left(P(a) + Q(a) + 2\sqrt{P(a)Q(a)} \right) \right) \\ &= H^2(P, Q) \left(1 + \sum_{a \in \Omega} \sqrt{P(a)Q(a)} \right) = H^2(P, Q) \left(2 - \left(1 - \sum_{a \in \Omega} \sqrt{P(a)Q(a)} \right) \right) \\ \text{(Remark 2)} &= H^2(P, Q) (2 - H^2(P, Q)) \end{aligned}$$

□

Definition 6. The Kullback–Leibler (KL) divergence between P and Q is:

$$D_{KL}(P||Q) := - \sum_{a \in \Omega} P(a) \ln \frac{Q(a)}{P(a)}$$

Note that KL-divergence is not a metric and asymmetric in P and Q . One important fact is:

Remark 3.

$$D_{KL}(P||Q) \iff P = Q$$

To connect the Hellinger distance with KL-divergence, we have the following bound:

Lemma 7.

$$H^2(P, Q) \leq 1 - \exp\left(-\frac{1}{2}D_{KL}(P||Q)\right)$$

Proof.

$$\begin{aligned} 1 - H^2(P, Q) &= \sum_{a \in \Omega} \sqrt{P(a)Q(a)} = \exp\left(\ln\left(\sum_{a \in \Omega} \sqrt{P(a)Q(a)}\right)\right) \\ &= \exp\left(\ln\left(\sum_{a \in \Omega} P(a) \sqrt{\frac{Q(a)}{P(a)}}\right)\right) \\ &= \exp\left(\ln\left(\mathbb{E}_{a \sim P} \sqrt{\frac{Q(a)}{P(a)}}\right)\right) \\ (\text{Jensen's Inequality}) &\geq \exp\left(\sum_{a \in \Omega} P(a) \ln \sqrt{\frac{Q(a)}{P(a)}}\right) \\ &= \exp\left(-\frac{1}{2}D_{KL}(P||Q)\right) \end{aligned}$$

□

To connect the total variacne with KL-divergence, we have the following bounds:

Lemma 8. The Pinsker's Inequality is:

$$\Delta(P, Q) \leq \sqrt{D_{KL}(P||Q)}$$

Proof. from lemma 5 and 7 we have:

$$\begin{aligned} \Delta(P, Q) &\leq \sqrt{2H^2(P, Q)} \\ &\leq \sqrt{2\left(1 - \exp\left(-\frac{1}{2}D_{KL}(P||Q)\right)\right)} \\ (\text{by } e^{-x} \geq 1 - x) &\leq \sqrt{2\left(1 - \left(1 - \frac{1}{2}D_{KL}(P||Q)\right)\right)} \\ &= \sqrt{D_{KL}(P||Q)} \end{aligned}$$

□

Lemma 9. *The High Probability Pinsker's Inequality is:*

$$\Delta(P, Q) \leq 1 - \frac{1}{2} \exp(-D_{KL}(P||Q))$$

Proof. From lemma 5, we have:

$$\begin{aligned} \Delta(P, Q) &\leq \sqrt{1 - (1 - H^2(P, Q))^2} \\ (\text{by } \sqrt{1-x} &\leq 1 - \frac{1}{2}x) &\leq 1 - \frac{1}{2} (1 - H^2(P, Q))^2 \\ (\text{by Lemma 7}) &\leq 1 - \frac{1}{2} \exp(-D_{KL}(P||Q)) \end{aligned}$$

□

A few comments on these two inequalities:

- when $D_{KL}(P||Q)$ is small, Lemma 8 gives a much tighter bound on $\Delta(P, Q)$ yet Lemma 9 gives loose upper bound at around 0.5.
- when $D_{KL}(P||Q)$ is large, Lemma 8 gives a useless upper bound since $\Delta(P, Q) \leq 1$. However Lemma 9 gives a more refined bound.